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... A simple **path** P from s to t will be called an ϵ -**shortest path** if $\text{length}(P) \leq (1 + \epsilon)d(s, t)$. We let $\epsilon \sigma_{st}$ denote the number of ϵ -**shortest paths** between ...

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... $a \cup b \cup a \cup 0 \cup 1 \cup 2 \cup 3 \cup 4 \dots S = \{aa \in \{a\} \wedge aa \in S \wedge aa \in S\} \cup aa \in \{\epsilon\}$... Examples:

shortest path, $(x \in) \cup L$. Solution method is to fuse the ...

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... and Agarwal [4] provided an algorithm that computes a **path** on a, possibly non-convex, polyhedron that is at most $7(1 + \epsilon)$ times the **shortest path** length; it ...

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... a routing table: o Entry for each destination o Estimated **shortest** distance to destination o Next router on **shortest path** a d e f c b c 4 f c 3 e c 2 d c 1 c b ...

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$(1+\epsilon)$ and shortest path

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